

73rd MORSS CD Cover Page

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Presented in (input and Bold one): (WG 27, CG, Special Session, Poster, Demo, or Tutorial)

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Report Documentation Page

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Purpose

- Performance as a variable in decision risk assessment
- Define the relationship of system availability from acquisition development to battlefield consequences.
- Define the cost risk methodology



System Performance Operational Risk Assessment Tool (SPORAT) Concept

INPUTS

ELEMENTS

- CONTRACTOR/GOV DATA-BASES
 - · · COST
 - ••SCHEDULE
 - • PERFORMANCE
- COST, SCHEDULE PERFORMANCE ANALYSIS

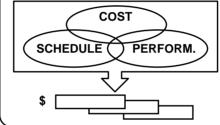
PRODUCTS

- COST, SCHEDULE PERFORMANCE BASELINES
- TRACKING SYSTEM
- RISK FORECASTS
- IMPACTS OF CHANGES
- WHAT IF's

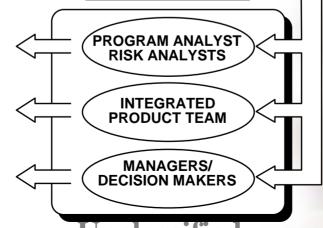
TOOLS

SPORAT SIMULATION

ELEMENT-LEVEL SIMULATION



USER GROUPS



SPORAT CAPABILITIES

<u>COST</u> CAN BE MODELED USING A WIDE RANGE OF DATA, BCE, PMA, CPR, ETC.

SCHEDULE CAN BE MODELED USING ARTEMIS, OPENPLAN, MACPROJECT PRO, AND MANY OTHERS.

<u>PERFORMANCE</u> IS DERIVED FROM TPMS, TRDS, ELEMENT SIMULATIONS (EADSIM, TACSIM, RADCAM, etc.), ACTUAL TEST DATA, EXPECTED TEST DATA, OR THEORETICAL ANALYSIS.

THE <u>PROBLEM</u> CAN BE MODELED AT ANY LEVEL FROM COMPONENT TO SYSTEM OR A COMBINATION OF VARIOUS LEVELS.

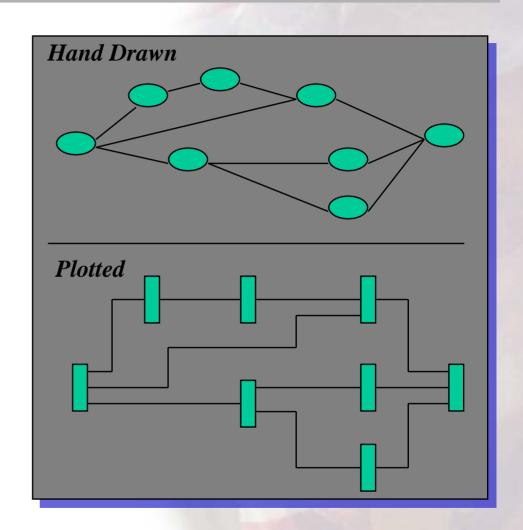
COST, SCHEDULE AND PERFORMANCE
CAN BE REPRESENTED AS
MATHEMATICAL FORMULAS OR
PROBABILITY DISTRIBUTIONS OR A
COMBINATION OF BOTH.

THE <u>NETWORK LOGIC</u> IS FLEXIBLE ENOUGH TO MODEL COMPLEX INTERRELATIONSHIPS SUCH AS TEST FAILURES, REDESIGN AND RETEST OF COMPONENTS OR SYSTEMS, THUS, PROVIDING THE PROBABLE TIME, COST AND SYSTEM PERFORMANCE ASSOCIATED WITH SUCH A FAILURE.



Network Development

- Logic network of project
- Initial development by benchmark
- Decomposition of benchmark activities
- Assignment of activity durations
- IPT quality review
- Input logic activities into SPORAT
- IPT final verification and validation





Overall TPP Matrix

TECHNICAL PERFORMANCE	APPLIED		CONDITIONS FOR DRAW	CONSEQUENCES IF A FAILURE OCCURS				
PARAMETER			I ON BRAW	TYPE	HARDWARE	SOFTWARE		
TRACK FILE OBJECTS (NUMBER)	BM 0.5 BM 1.0 BM 2.0	N311-N370 N591-N600 N730-N731	NOR MAL DISTRIBUTION MAX 200, MIN 1 BM 0.5 - MEAN 100, 3 SEC	REWORK REWORK		TIME & COST 5%-10% DIST. DIST. 35%-50%		
TRACK UPDATE LATENCY (SECONDS)	BM 0.5 BM 1.0 BM 2.0	N465-N490 N601-N602 N740-N741	STD 10 BM 1.0 - MEAN 100, 3 SEC STD 10	REWORK HI	TIME & COST 10%-20% DIST.			
TRACK PURGE (SECONDS)	BM 1.0	N604-N605	BM 2.0 - MEAN 100, 3 SEC STD 5	REWORK		TIME & COST 35%-50%		
MESSAGE HANDLING RATE (MSGS PER SEC)	BM 1.0	N652-N660	GAMMA DIST. R=2 MAX 50, MIN 5, 1 SEC	REWORK	15% HW COST	TIME & COST 5%-10% DIST.		
MESSAGE HANDLING LATENCY (SECONDS)	BM 1.0	N654-N655	MEAN 17 STD 12	REWORK		TIME & COST 10%-20% DIST.		
C ² PROCESSING			NORMAL DIST. MAX 200, MIN 100 MEAN 100 STD 30					

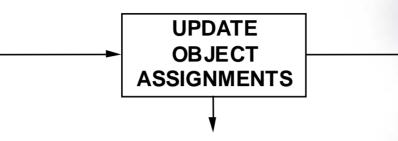
[•] SOFTWARE REWORK NOT LESS THAN ONE DAY

[•] HARDWARE UPGRADE INCLUDES COST PLUS ONE WEEK DELIVERY DELAY



How TPP's are Applied

- Tracked Objects Database
- Incoming Sensor Data Sets
- Designation of Objects to be Updated



 New Object-Data Association

- Accuracy of Correlations
- Number of Hits Needed for Correlation
- Correlation Cycle Timeline
- False Correlations
- Correctness of Correlation Thresholds
- Robustness in Utilization of Inaccurate or Incomplete Sensor Data
- Erroneous Object Updates
- Are Correlation Thresholds Being Met?
- Task Processing Timelines

Technical Performance Parameter

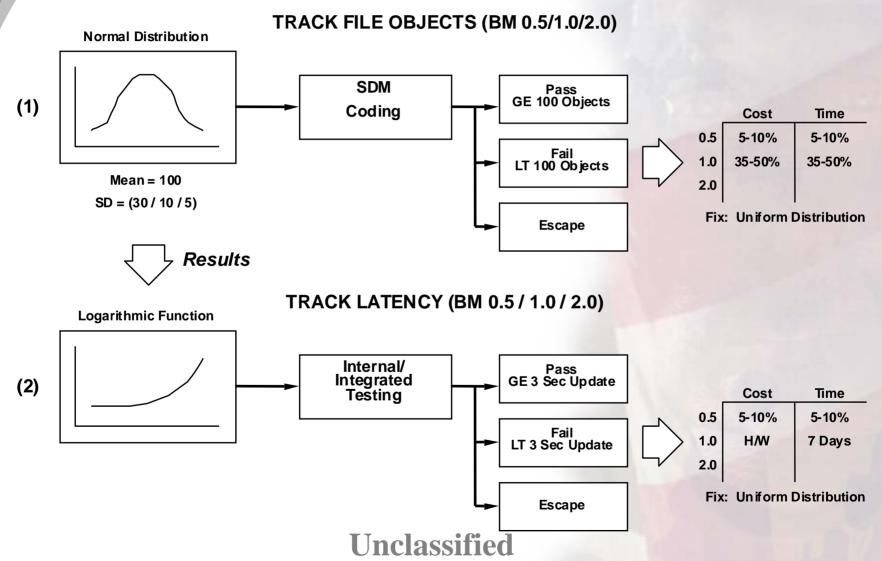
- Accuracy of Object Correlations
- Number of Hits Needed for Correlation
- Correlation Cycle Timeline

Metric

- Percent of Correct Correlations
- Average Counts of Hits (#)
- Average Time

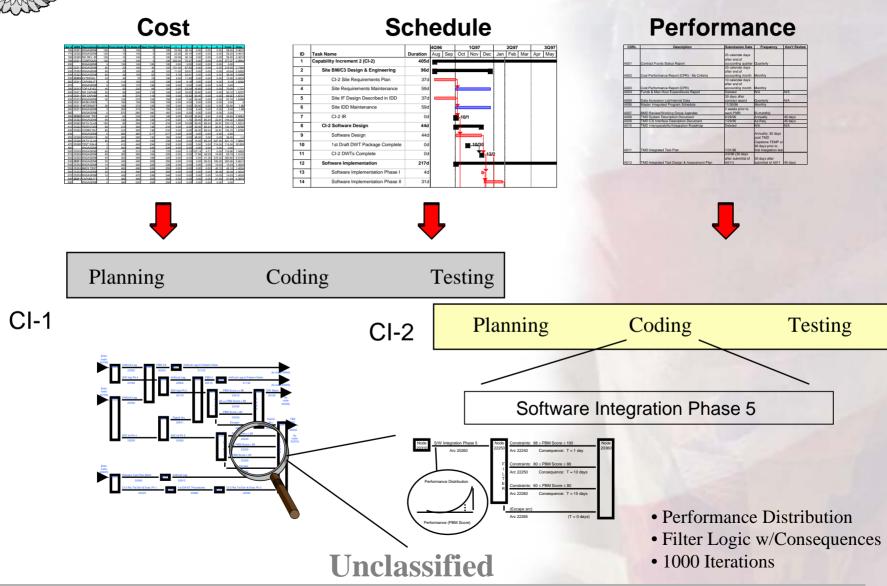


Application of TPPs



RADITION OF EXCELLENGE

Software Integration Phase 5

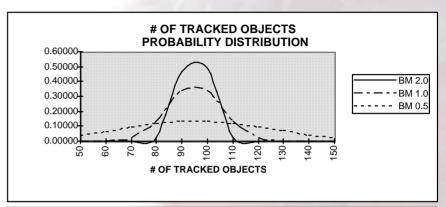


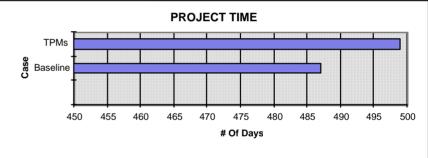


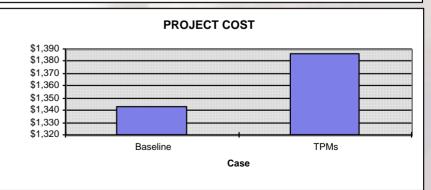
Tracked Objects Technical Performance

Analysis Steps

- Developed Baseline Network
- Strategically Placed Technical Performance Distributions at Appropriate Benchmark Activities
- Developed and Analyzed Pass/Fail
 Performance Criteria
- Accumulated Progressive Technical Performance With Narrowed Distributions
- Assessed Cost/Schedule/Technical Performance
- Produced Graphical Results for Cumulative Risk Functions

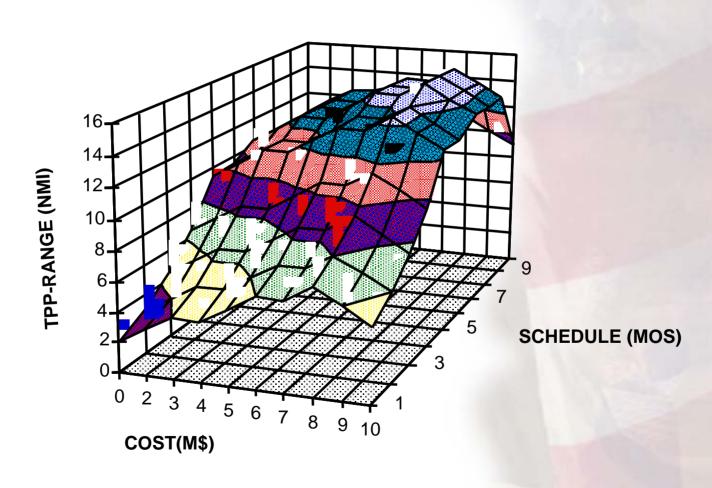








3D Dynamics of Cost, Schedule & Performance Risk





Approach to Software Development Program

For Each Increment Build:

Pre-Demo Reg Def. Design & Code Int & Test Demo Gov works w/ Cont to: Gov: Gov: Demo: Define Inc Objectives Understands tech McCabe Tool Cont & Gov share in details (or equiv) Trace to TPM's/ SE Req tech briefing Define Pre-demo Chk List Witness kev Guide issue Show traceability: testing resolution TPMs/ SE Req to Chk Verify Executability List, Demo **Understand:** Doc decisions "Score Card" • Objectives •• Tasks Development • Resources Rea'd Track issue Performance: resolution Assess Cont Plan S/W Metrics "Can it work ?" Pre-demo Test: Defects Removed • S/W Rel, Maint. Informal Issue Résolution Key to Success ... Verity Chk List realistic ... actuals Eng Lvl ... DTC focus !! Start S/W Metrics ... Goal: Calibrate our IPT to support Cont to grow S/W Metrics Data Base Foundation . . . Inc Build Executability Verification Wkly Wkly Wkly Wkly Status Status Status Status



TPP/TPM Integrated Assessment Capabilities

Technical Design Minimums

- Design goal achieved
- What resources
- Probability of goal
- Cost impact

Track Purge Applied

- Resources need
- Could the goal have been met
- Better probability of success

Deobligation of Funds

- Least affected
- Completion Affected
- Achievement of next event

v Windfall Funds

- Acceleration of tasks
- New technical goals

v New Requirement

- Evaluate costs
- Impact on original schedule

v Network Path Analysis

- Time slices
- Probability of success

v Technical Goal Not Achievable

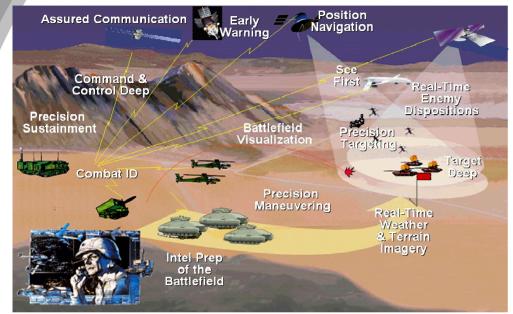
- What resources needed
- What-ifs



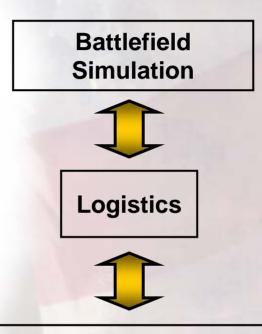
System Operational Availability



Technical Risk & Logistics Analysis



- Performance Risk Identification / Mitigation
- System Maintenance Concept
- Weapon System Concept Trades
- Sensor vs. Interceptor Trades
- Supportability Design Criteria
- Cost



Program Cost Schedule Performance

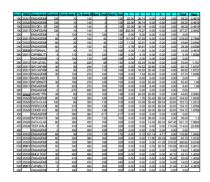


Life Cycle Cost/ Contractor



Radar Cost/Schedule/Performance

Contract Cost



Contractor Schedule

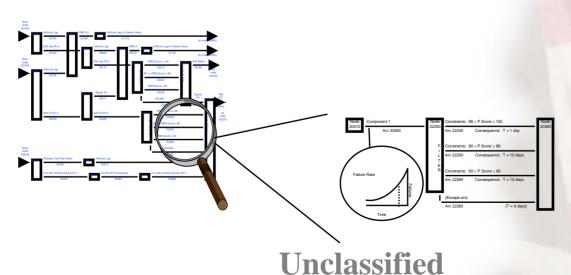
			4Q96	;		1Q97			2Q97	,		3Q97
ID	Task Name	Duration	Aug	Sep	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May
1	Capability Increment 2 (CI-2)	405d			=		=	_	_		-	
2	Site BM/C3 Design & Engineering	96d	_									
3	CI-2 Site Requirements Plan	37c	100000		h							
4	Site Requirements Maintenance	59c					000000					
5	Site IF Design Described in IDD	37c		00000000	H							
6	Site IDD Maintenance	59c					555555					
7	CI-2 IR	0d			10/	1						
8	CI-2 Software Design	44d		ı	-	_						
9	Software Design	44c			Ť	00000000	ካ					
10	1st Draft DWT Package Comple	0d			1	10/3	30					
11	CI-2 DWTs Complete	0d				٦	12/	2				
12	Software Implementation	217d		1	+		_	_	_			
13	Software Implementation Phase	4d					ď					
14	Software Implementation Phase	31c					+					

Component Failure Rates

CDRL	Description	Submission Date	Frequency	Gov't Review	
		25 calendar days after end of			
4001	Contract Funds Status Report	accounting quarter	Quarterly		
A002	Cost Performance Report (CPR) - No Criteria	20 calendar days after end of accounting month	Monthly		
A003	Cost Performance Report (CPR)	10 calendar days after end of accounting month	Monthly		
A004	Funds & Man-Hour Expenditures Report	Deleted	N/A	N/A	
A005	Data Accession List/Internal Data	30 days after contract award	Quarterly	N/A	
4006	Master Integrated Program Schedule	11/30/96	Monthly		
4007	BMD Review/Working Group Agendas	2 weeks prior to each PMR	Bi-monthly		
4008	TMD System Description Document	6/28/96	Annually	45 days	
1009	TMD C3I Interface Description Document	1/29/96	As Reg.	45 days	
A010	TMD Interoperability/Integration Roadmap	Deleted	N/A	N/A	
A011	TMD Integrated Test Plan	1/31/96	Annually, 30 days post TMD Capstone TEMP or 90 days prior to first Integration test		
A012	TMD Integrated Test Design & Assessment Plan	3/2/96 (30 days after submittal of A011)	30 days after	45 days	







- Failure Distribution
- Filter Logic w/Consequences
- 1000 Iterations



Radar Operational Availability Battlefield Environment

